

## On the Trace of the Correlation Rigid-Body Tensor

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It is shown that if the eigenvalues of the TLS matrix  $C_{66}$  are all positive, then the trace of  $S$  must lie within an open interval, which is effectively determined. Further Scheringer's equation for the estimate of the trace of  $S$  is shown to have in this interval exactly one root which is simultaneously the point of the maximum of the determinant of the TLS matrix  $C_{66}$ .

### 1. Introduction\*

Schomaker & Trueblood (1968) showed that the external vibrations of almost rigid molecules can be described by three tensors  $T$ ,  $L$  and  $S$ . However, trace ( $S$ ) cannot be determined from diffraction data since only the differences  $S_i^i - S_j^j$  enter into the calculation. The condition, trace ( $S$ )=0, was chosen by them for practical purposes. But this condition does not remove the indeterminacy of trace ( $S$ ).

Scheringer (1973 - hereafter SCHE) pointed out that we should know trace ( $S$ ), at least approximately, for a lattice-dynamical interpretation of the TLS tensor. He found that the limits for trace ( $S$ ) follow from the fact that the matrix  $C_{66}$  must be positive definite. He gave also an estimate for the trace ( $S$ ) originating in the lattice dynamics of molecular crystals. We quote his equation (4.15):

$$\{C_{66}^{-1}(K)\}_{14} + \{C_{66}^{-1}(K)\}_{25} + \{C_{66}^{-1}(K)\}_{36} = 0. \quad (1.1)$$

The principal purpose of this paper is to show that an estimate of the trace ( $S$ ), for which matrix  $C_{66}(K)$  is positive definite, follows uniquely from (1.1). This supports the lattice-dynamical interpretation of the TLS tensors indicated by SCHE. Therefore we shall try to answer the following questions:

(i) What is the shape of the set  $M$  of all  $K$  for which the TLS matrix  $C_{66}(K)$  is positive definite?

(ii) How many roots has (1.1) in the set  $M$ ?

Mathematical analysis of these questions will also show an effective way of finding the limits and an estimate of trace ( $S$ ). It is obvious that the limits for trace ( $S$ ) found by mathematical analysis are not narrower than those previously established [SCHE (4.5)] but about the same.

### 2. Mathematical analysis\*

*Theorem 1:* The set  $M$  is an open interval.

*Proof:* The matrix  $C$  is positive definite (see SCHE Appendix) and therefore at least one  $K$  must exist for which the matrix  $C_{66}(K)$  is also positive definite. Thus  $M$  is not void. Let  $K_1 \in M$ . According to Lemma 1 of Appendix I the principal minor determinants  $A_1, A_2,$

$A_3, A_4(K_1), A_5(K_1), A_6(K_1)$  are positive. However, these determinants are continuous functions of  $K$ , the

$$A_1, A_2, A_3 \quad (2.1)$$

being constants and the

$$A_4(K), A_5(K), A_6(K) \quad (2.2)$$

being polynomials of second, fourth and sixth orders respectively. Consequently, a region for this point  $K_1$  may be found where the determinants (2.1) and (2.2) are positive and therefore the matrix  $C_{66}(K)$  positive definite. This means that  $M$  is an open set.

Further let  $K_1, K_2 \in M$ . According to SCHE (Appendix) the matrix  $C_{66}(K_1) + C_{66}(K_2)$  is positive definite and hence the matrix  $[C_{66}(K_1) + C_{66}(K_2)]/2 = C_{66}[(K_1 + K_2)/2]$  is positive definite as well. Thus  $(K_1 + K_2)/2 \in M$ . This means that  $M$  must be an open interval and Theorem 1 is proved.

*Theorem 2:* The roots of equations ( $E_4$ ), ( $E_5$ ) and ( $E_6$ ) fulfil the inequalities:

$${}^4K_1 \leq {}^5K_2 \leq {}^6K_3 < {}^6K_4 \leq {}^5K_3 \leq {}^4K_2 \quad (2.3)$$

and the set  $M$  is the interval:

$$({}^6K_3, {}^6K_4). \quad (2.4)$$

*Proof:* The determinants (2.1) being independent of  $K$  and positive (see Lemma 1 of Appendix I), only the polynomials (2.2) will be investigated. For the matrix  $C_{66}(K)$  to be positive definite it is necessary that (2.2) be simultaneously positive. This condition implies the form (2.4) of the set  $M$ . The behaviour of the polynomials (2.2) for  $K \rightarrow \pm \infty$  is governed by the coefficients of the highest-order terms. Writing:

$$A_4(K) = -[T^{22}T^{33} - (T^{23})^2]K^2 + \sum_{n=0}^1 a_n K^n$$

$$A_5(K) = T^{33}K^4 + \sum_{n=0}^3 b_n K^n$$

$$A_6(K) = -K^6 + \sum_{n=0}^5 c_n K^n,$$

we see that the expression  $T^{22}T^{33} - (T^{23})^2$ , being a principle minor determinant of the matrix  $C_{66}(K)$  independent of  $K$ , is positive in view of Note 1 of Appendix I. For the same reason  $T^{33} > 0$ . Thus:

\* Symbols are summarized in Appendix III.

$$K \rightarrow \pm\infty \Rightarrow \Delta_4(K) \rightarrow -\infty \quad (2.5a)$$

$$K \rightarrow \pm\infty \Rightarrow \Delta_5(K) \rightarrow +\infty \quad (2.5b)$$

$$K \rightarrow \pm\infty \Rightarrow \Delta_6(K) \rightarrow -\infty. \quad (2.5c)$$

From Theorem 1, Lemma 1 of Appendix I and (2.5a) it follows that the equation ( $E_4$ ) has two roots  ${}^4K_1 < {}^4K_2$  and:

$$K \in ({}^4K_1, {}^4K_2) \Rightarrow \Delta_4(K) > 0 \quad (2.6)$$

$$K \notin \langle {}^4K_1, {}^4K_2 \rangle \Rightarrow \Delta_4(K) < 0.$$

Since the numbers (2.1) are positive and  $\Delta_4({}^4K_1) = \Delta_4({}^4K_2) = 0$  the rank of matrix  $C_{44}(K)$  at the points  ${}^4K_1, {}^4K_2$  is equal to 3. According to Lemma 2 of Appendix I,  $C_{44}(K)$  has at these two points three positive eigenvalues and one equal to zero. Applying the Lemma of Appendix II we get:

$$\Delta_5({}^4K_1) \leq 0 \quad \Delta_5({}^4K_2) \leq 0. \quad (2.7)$$

The roots of equation ( $E_5$ ) fulfil then the following inequalities [see Theorem 1, Lemma 1 of Appendix I and (2.5b), (2.6), (2.7)]:

$${}^5K_1 \leq {}^4K_1 \leq {}^5K_2 < {}^5K_3 \leq {}^4K_2 \leq {}^5K_4. \quad (2.8)$$

Further we shall confine ourselves to the case when all roots of equation ( $E_5$ ) are simple. Though the remaining cases are more complicated, they give the same results.† Under our assumption we have:

$$\begin{aligned} K \in (-\infty, {}^5K_1) &\Rightarrow \Delta_5(K) > 0 \\ K \in ({}^5K_1, {}^5K_2) &\Rightarrow \Delta_5(K) < 0 \\ K \in ({}^5K_2, {}^5K_3) &\Rightarrow \Delta_5(K) > 0 \\ K \in ({}^5K_3, {}^5K_4) &\Rightarrow \Delta_5(K) < 0 \\ K \in ({}^5K_4, +\infty) &\Rightarrow \Delta_5(K) > 0. \end{aligned} \quad (2.9)$$

From (2.6), (2.8) and (2.9) it follows:

$$\Delta_4(K) > 0 \ \& \ \Delta_5(K) > 0 \Leftrightarrow K \in ({}^5K_2, {}^5K_3). \quad (2.10)$$

The numbers (2.1) are positive and  $\Delta_4({}^5K_1) \leq 0$ ,  $\Delta_4({}^5K_2) \geq 0$ ,  $\Delta_5({}^5K_1) = \Delta_5({}^5K_2) = 0$ . The following four cases have been considered separately.

(i)  $\Delta_4({}^5K_1) < 0$  &  $\Delta_4({}^5K_2) > 0$

Here the rank of matrix  $C_{55}(K)$  at the points  ${}^5K_1, {}^5K_2$  is equal to 4. Lemma 2 of Appendix I implies that the matrix  $C_{55}({}^5K_1)$  has three positive, one negative and one zero eigenvalues and the matrix  $C_{55}({}^5K_2)$  four positive and one zero eigenvalues. Applying the Lemma of Appendix II we get:

$$\Delta_6({}^5K_1) \geq 0 \quad \Delta_6({}^5K_2) \leq 0. \quad (2.11a)$$

(ii)  $\Delta_4({}^5K_1) = 0$  &  $\Delta_4({}^5K_2) > 0$

At the point  ${}^5K_1$  the situation is similar to that of the previous case. However, at  ${}^5K_1$  the sequence  $\Delta_1, \Delta_2, \Delta_3, \Delta_4(K), \Delta_5(K), \Delta_6(K)$  cannot be used for determining the signs of eigenvalues, since the rank of  $C_{55}({}^5K_1)$  is equal

to four (see Note 2 of Appendix I). The last statement follows from the assumption that the roots of ( $E_5$ ) are simple. Then  $d[\Delta_5(K)]/dK$  is different from zero for  $K = {}^5K_1$ . But  $d[\Delta_5(K)]/dK$  is a sum of minors of order four, so that at least one of them must be different from zero and the rank of  $C_{55}({}^5K_1)$  is four as stated above. Thus the signs of eigenvalues may be determined from the continuity of the eigenvalues of  $C_{55}(K)$  as functions of  $K$  and the behaviour of  $\Delta_4(K)$  and  $\Delta_5(K)$  in the neighbourhood of  ${}^5K_1$ . We find that  $C_{55}({}^5K_1)$  has three positive, one negative and one zero eigenvalues and get in view of the lemma of Appendix II again the inequalities (2.11a).

(iii)  $\Delta_4({}^5K_1) < 0$  &  $\Delta_4({}^5K_2) = 0$

The discussion is quite analogous to the previous one.

(iv)  $\Delta_4({}^5K_1) = 0$  &  $\Delta_4({}^5K_2) = 0$

The eventuality cannot occur since the roots of ( $E_5$ ) are simple and (2.8) holds. Thus the inequalities (2.11a) are true in all cases. Performing a similar analysis at the points  ${}^5K_3, {}^5K_4$  we obtain:

$$\Delta_6({}^5K_3) \leq 0 \quad \Delta_6({}^5K_4) \geq 0. \quad (2.11b)$$

The roots of equation ( $E_6$ ) fulfil [see Theorem 1, Lemma 1 of Appendix I and (2.5c), (2.10), (2.11)]:

$$\begin{aligned} {}^6K_1 \leq {}^5K_1 \leq {}^6K_2 \leq {}^5K_2 \leq {}^6K_3 < {}^6K_4 \leq {}^5K_3 \\ \leq {}^6K_5 \leq {}^5K_4 \leq {}^6K_6. \end{aligned} \quad (2.12)$$

Further:

$$K \in ({}^6K_3, {}^6K_4) \Rightarrow \Delta_6(K) > 0. \quad (2.13)$$

From (2.10), (2.12) and (2.13) it follows:

$$\begin{aligned} \Delta_4(K) > 0 \ \& \ \Delta_5(K) > 0 \ \& \ \Delta_6(K) > 0 \\ \Leftrightarrow K \in ({}^6K_3, {}^6K_4). \end{aligned} \quad (2.14)$$

This means that the set  $M$  is the interval (2.4). The inequalities (2.3) follow from (2.8) and (2.12) and the proof of Theorem 2 is completed.

*Theorem 3:* (1.1) has in the set  $M$  exactly one solution, say  $K_0$ , fulfilling the maximum condition:

$$\Delta_6(K_0) = \underset{K \in M}{\text{Max}} \Delta_6(K).$$

*Proof:* Writing (1.1) in the form:

$$\frac{A_{14}(K) + A_{25}(K) + A_{36}(K)}{\Delta_6(K)} = 0 \quad (2.15)$$

and having in mind that:

$$\frac{d}{dK} [\Delta_6(K)] = 2[A_{14}(K) + A_{25}(K) + A_{36}(K)] \quad (2.16)$$

[since  $C_{66}(K)$  is symmetric], we can see that (1.1) is equivalent to the following condition in the set  $M$ :

$$\frac{d}{dK} [\Delta_6(K)] = 0. \quad (2.17)$$

Considering the behaviour of the function  $\Delta_6(K)$  [see (2.12), (2.13)] we get Theorem 3.

\* See Appendix III.

† The detailed discussion is available from the author.

3. Conclusions

The above theorems enable us to put limits on trace (S) [trace (S)=3K] and to estimate its value in the following simple way.

We find first the coefficients of polynomials  $\Delta_4(K)$ ,  $\Delta_5(K)$ ,  $\Delta_6(K)$ . The knowledge of these makes it possible to determine subsequently such roots of  $(E_4)$ ,  $(E_5)$  and  $(E_6)$  which fulfil inequalities (2.3). In this way we get the limits for trace (S). The next step is to find the derivative  $d[\Delta_6(K)]/dK$  and to determine its root lying in the interval  $M$ . In this way we get an estimate for trace (S).

This method presents a direct and simpler approach of determining the limits of and the estimate for trace (S) than the numerical methods described earlier (SCHE).

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APPENDIX I

For the convenience of the reader we quote two well-known propositions concerning matrix theory [see e.g. Gantmacher (1953)]. Supposing A is a symmetric matrix of order  $n$  we denote:

$$D_1 = A_{11}, D_2 = \det \begin{pmatrix} A_{11} & A_{12} \\ A_{12} & A_{22} \end{pmatrix}, \dots, D_n = \det \begin{pmatrix} A_{11} & A_{12} & \dots & A_{1n} \\ A_{12} & A_{22} & \dots & A_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ A_{1n} & A_{2n} & \dots & A_{nn} \end{pmatrix}.$$

Lemma 1: The matrix A is positive definite (i.e. its eigenvalues are positive) if and only if:

$$D_1 > 0, D_2 > 0, \dots, D_n > 0.$$

Note 1: It follows that all principal minor determinants of a positive definite matrix are positive.

Lemma 2: Let  $r$  be the rank of matrix A, let  $D_k \neq 0$  for  $k=1, \dots, r$ . Then the number of zero eigenvalues is equal to  $n-r$ . The number of the negative eigenvalues is equal to the number of changes of signs in the sequence  $1, D_1, \dots, D_r$ .

Note 2: The sequence  $1, D_1, D_2, \dots, D_r$  cannot be used to determine the number of negative eigenvalues if, in particular,  $D_r = 0$ .

APPENDIX II

Lemma: Let A be a symmetric square matrix of order  $n$  which has one zero eigenvalue and an odd (or even) number of negative eigenvalues. Let the matrix B originate from A in the following way:

$$B = \begin{pmatrix} A_{11}A_{12} \dots A_{1n}B_1 \\ A_{12}A_{22} \dots A_{2n}B_2 \\ \vdots \quad \vdots \quad \ddots \quad \vdots \\ A_{1n}A_{2n} \dots A_{nn}B_n \\ B_1 \ B_2 \ \dots \ B_n \ B_{n+1} \end{pmatrix}.$$

Then  $\det(B) \geq 0$  [or  $\det(B) \leq 0$ , respectively].

Proof: Certainly an orthogonal matrix R may be found in such a way that:

$$R^T A R = \Lambda.$$

Where  $\Lambda$  is a diagonal matrix with  $\lambda_{nn}=0$  and  $R^T$  denotes the transpose of R. Let D be the row matrix  $(B_1, B_2, \dots, B_n)$  and O the row matrix consisting of  $n$  zero elements. Taking the auxiliary orthogonal matrix Q:

$$Q = \begin{pmatrix} R & O^T \\ O & I \end{pmatrix}$$

we get

$$Q^T B Q = \begin{pmatrix} \Lambda & R^T D^T \\ DR & B_{n+1} \end{pmatrix} \Rightarrow \det(Q^T B Q) = \det(B) = -\lambda_{11}\lambda_{22} \dots \lambda_{n-1n-1} [(DR)_n]^2$$

which makes the Lemma clear.

APPENDIX III

Symbols for quantities

- C = the mean-square-amplitude matrix
- T = the translation tensor
- L = the libration tensor
- S = the correlation tensor with trace (S)=0
- S(K) = the correlation tensor whose trace is equal to  $3K$ .
- $S_j^j(K) = S_j^j + K; S_i^i(K) = S_i^i$  for  $(i \neq j)$
- where  $S_j^j$  ( $i, j=1, 2, 3$ ) are the components of S.

$$C_{66}(K) = \text{the matrix} \begin{pmatrix} T & S^T(K) \\ S(K) & L \end{pmatrix}$$

- where  $S^T(K)$  denotes the transpose of S(K)
- $A_{ij}(K)$  = the cofactor of  $\{C_{66}(K)\}_{ij}$   $i, j=1, 2, \dots, 6$
- $C_{44}(K)$  = the matrix which arises from  $C_{66}(K)$  by deleting the fifth and sixth rows and columns
- $C_{55}(K)$  = the matrix which arises from  $C_{66}(K)$  by deleting the 6th row and column
- $\Delta_1 = T^{11}, \Delta_2 = \det \begin{pmatrix} T^{11} & T^{12} \\ T^{12} & T^{22} \end{pmatrix}, \dots, \Delta_6(K) = \det [C_{66}(K)]$
- = the sequence of principal minor determinants of the matrix  $C_{66}(K)$
- $(E_i)$  = the equation  $\Delta_i(K) = 0$  ( $i=4, 5, 6$ )
- ${}^i K_1 \leq {}^i K_2 \dots \leq {}^i K_j$  = the real roots of the equation  $(E_i)$  ( $i=4, 5, 6$ ).

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